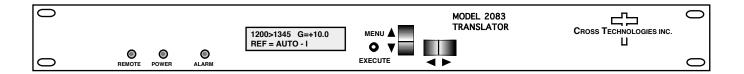
Instruction Manual

Model 2083-1617 Block Translator

February 2023, Rev. 0



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INSTRUCTION MANUAL

MODEL 2083-1617 Block Translator

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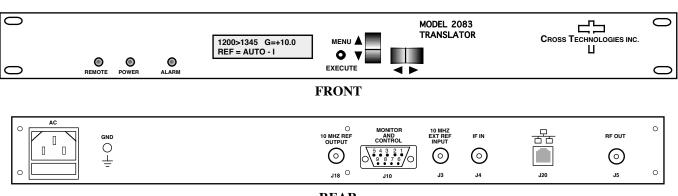
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MODEL 2083-1617 Block Translator

1.0 General

1.1 Equipment Description

2083-1617 Block Translator - The 2083-1617 Block 1200 ±400 to 1345 ±400 Translator converts a 1200 ±400 MHz block to 1345 ±400 MHz block with no spectrum inversion, low group delay and flat frequency response. The 1200 ±400 MHz input is mixed with synthesized local oscillator (LO) signals, first to 3800 MHz center frequency and finally to the 1345 ±400 MHz block output. Multifunction switches select the gain and internal or external 10 MHz. The input frequency band, output frequency band, internal or external reference, and gain (0 to +20 dB, selectable in 0.5 ±0.5 dB steps) settings appear on the LCD display. Front panel LEDs provide indication of DC power (green), PLL alarm (red), and remote operation (yellow). Remote operation allows setting the overall gain and 10 MHz reference. Connectors are BNC female for RF input and output and for the external 10 MHz reference (+3± 3 dBm in). It is powered by a 100-240 ±10% VAC, 47-63 HZ input power supply and in a 1 3/4" X 19" X 16" rack mount chassis.



REAR

FIGURE 1.1 Model 2083-1617 Front and Rear Panels

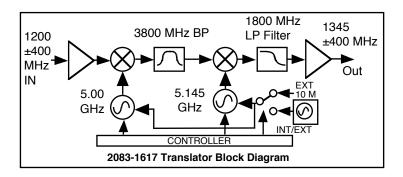


FIGURE 1.2 Model 2083-1617 Translator Block Diagram

1.2 Technical Characteristics

Input Impedance/RL	50Ω/15 dB				
Frequency	1200 ±400 MHz				
Input Composite Level	-30 to -10 dBm				
Input, max. no damage	+10 dBm				
Output Characteristics					
Impedance/RL	50Ω / 15 dB				
Frequency	1345 ±400 MHz				
Output Composite Level	-25 to -5 dBm at	Fc			
Output 1 dB Compression	+5 dBm, at maxir	mum gain, Fc			
Channel Characteristics					
Gain at Fc	0 to +20 dB, ±2.0	0 dB, selectable	in 0.5± 0.5 dB st	eps	
Frequency Response	± 1.5dB, Fc ±400) MHz; ± 0.5 dB	, Fc ±80 MHz; Gr	max	
Spurious, Inband	< -50 dBc in band See NOTE 1	d, signal depend	lent and signal in	dependent; -5 dB	m out; at Gm
Spurious, Out of Band	<-50 dBm, 0.5 - 1	.195 and 1.495	- 2.0 GHz, Gmax	See NOTE 1	
Frequency Sense	Non-inverting				
	*NOTE 1: dBc is	relative to the C	OMPOSITE Out	out Level	
Synthesizer Characteristics	•				
Translation; Accuracy	± 1.0 ppm max or	ver temp (±0.01	ppm, option-H)		
Reference	10 MHz Internal;	Internal / Extern	nal Selection		
Frequency Step	None, fixed frequ	ency			
Phase Noise @ Frequency	100 MHz	1kHz	10kHz	100kHz	1MHz
dBc/Hz	-60	-70	-80	-90	-100
Controls, Indicators		•			
Fc Translation	Direct readout Lo	CD			
Gain (MGC)	Direct readout Lo	CD; manual or r	emote selection		
External Ref.	Direct readout Lo				
Power, Alarm; Remote	Green LED; Red				
Remote	RS232C, 9600 E				
Other	1 112223, 3330 2	,			
RF In/RF Out Connector	BNC (female) 50	Ω, See Option C	Chart		
10 MHz Out Connector	BNC (female), 50				
Alarm/Remote Connector	1				
	DB9 (female); No or NC contact closure on Alarm 19 inch Standard Chassis 1.75" high x 16.0" deep				
Size	I 19 inch Standard	Chassis 1 75" h	11ah x 16 0" deen		

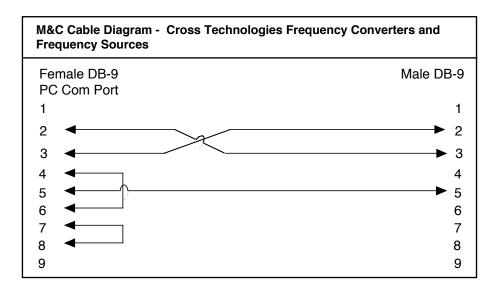
${\bf 1.2~Technical~Characteristics, continued...}$

Available Options (2083-1617 Block Translator)			
H -	High Stability (±0.01) Internal Reference		
W31-	0 to 50 degrees C operation		
Communication Int	erface / Standard RS232		
Q -	RS485 Remote Interface		
W8 -	Ethernet; with Web Browser		
W18 -	Ethernet; with Web Browser & SNMP		
W28 -	Ethernet; with TCP/IP, Telnet®		
W828 -	W8 +W18 +W28		
Connector /Impeda			
Std -	50Ω BNC (RF IN), 50Ω BNC (RF OUT)		
NN -	N - 50Ω N (RF In), 50Ω N (RF Out)		
SS -	50Ω SMA (RF In), 50Ω SMA (RF Out)		
Contact Cross Technologies for other options.			

1.3 Monitor and Control Interface

A) Remote Serial Interface

Protocol: RS-232C, 9600 baud rate, no parity, 8 data bits, 1 start bit, and 1 stop bit. (RS-232C, RS-422, or **RS-485** - **option -Q**)



Connector: Rear panel, DB-9 male

J10 Pinouts (RS-232C/422/485)			
Pin	Function		
1	Rx-		
2	Rx+ (RS-232C)		
3	Tx+ (RS-232C)		
4	Tx-		
5	GND		
6	Alarm Relay: Common		
7	Alarm Relay: Normally Open		
8	Not Used		
9	Alarm Relay: Normally Closed		

B) Status Request/Inquiries -

Table 1.0 lists the Status Request/Inquiries for the 2083-1617, and briefly describes them.

General Command Format - The general command format is {aaCND...}, where:

{ = start byte

aa = address (RS-485 only - option -Q)

C = 1 character, either C (command) or S (status)

N = 1 character command or status request

D = 1 character or more of data (depends on command)

} = stop byte

^{*} PLEASE NOTE: The two character {aa}(00-31) prefix, in the table below, should be used ONLY when RS-485, (OPTION-Q), is selected.

TABLE 1.2 2083-1617 St	atus Request/I	nquiries
Command	Syntax*	Description
Gain Inquiry	{aaSG}	returns: {aaSGxxxx}
		where:
		aa = unit address, range = 00 to 31, only used if interface is
		RS485, otherwise omit
		G = command code
		xxxx = gain in dB
		The unit will append the '>' character if the command is
		sucessfully processed.
Reference Mode Inquiry	{aaSE}	returns: {aaSEx}
		where:
		aa = unit address, range = 00 to 31, only used if interface is
		RS485, otherwise omit
		E = command code
		x = 0 if reference mode is internal, $x = 1$ if external,
		x = 2 if auto
		The unit will append the '>' character if the command is
		sucessfully processed.
Reference Status Inquiry	{aaSB}	returns: {aaSBx}
		where:
		aa = unit address, range = 00 to 31, only used if interface
		is RS485, otherwise omit
		B = command code
		x = 1 if the unit is using the external reference, $x = 0$
		if the unit is using the internal reference
		note: this inquiry is useful if the reference mode is auto and
		the user wants to know if the unit has switched to the
		internal reference.
		The unit will append the '>' character if the command is
		sucessfully processed.

Table 1.2, Status Request/Inquiries continued from page $7\dots$

Command	Syntax*	Description	
Alarm Inquiry	{aaSA}	returns: {aaSAx}	
		where:	
		aa = unit address, range = 00 to 31, only used if interface is	
		RS485, otherwise omit	
		A = command code	
		x = 0 if alarm is off, $x = 1$ if alarm is on.	
		The unit will append the '>' character if the command is	
		sucessfully processed.	
D 1 04 1 1 1 1 1 1 1 1 1	((((((((((((((((((((. (0)(2002	
Product/Model Info Inquiry	{aaSV}	returns {aaSV2083-xxxx yyyy ver5.xx}	
		where 2083-xxxx = product model	
		yyyy = list of options, if any	
		"ver" = separates model & options from firmware version	
		5.xx = firmware version	

C) Commands - Table 1.0 lists the M&C Commands for the 2083-1617, and briefly describes them. After a command is sent the 2083-1617 sends a return ">" indicating the command has been received and executed.

General Command Format - The general command format is {aaCND...}, where:

{ = start byte

aa = address (RS-485 only - option - Q)

C = 1 character, either C (command) or S (status)

N = 1 character command or status request

D = 1 character or more of data (depends on command)

} = stop byte

^{*} PLEASE NOTE: The two character {aa}(00-31) prefix, in the table below, should be used ONLY when RS-485, (OPTION-Q), is selected.

Table 1.3 2083-1617 M	&C Commands	
Command Function	Syntax*	Command Description
Set Gain	{aaCGxxxx}	where:
		aa = unit address, range = 00 to 31,
		only used if interface is RS485, otherwise omit
		G = command code
		xxxx = gain in 0.5 dB steps, may decimal point
		Range: = 0 to 20.0 in 0.5 dB steps
		example: {CG155}
		Will set the unit's gain to 15.5 dB.
		Note: The decimal point is assumed if not included, i.e.
		{CG155} is parsed the same as {CG15.5}.
		The unit will reply with the '>' character if the command
		is sucessfully processed.
Set Reference Mode	{aaCEx}	where:
		aa = unit address, range = 00 to 31, only used if interface
		is RS485, otherwise omit.
		E = command code
		x = 0 to set to internal reference, $x = 1$ to set to
		external reference, $x = 2$ to set to auto reference.
		example: {CE2}
		Will set the reference mode to Auto.
		The unit will reply with the '>' character if the
		command is sucessfully processed.

Table~1.3, M&C~Commands~continued~from~page~9...

Command	Syntax*	Description
Set Remote Off	{aaCRO}	where:
		aa = unit address, range = 00 to 31, only used if interface is
		RS485, otherwise omit
		R = command code
		0, ascii number zero.
		example: {CR0}
		Will disable the unit's serial M&C port.
		The unit will reply with the '>' character if the command
		is sucessfully processed.
		(Note: this command only affects the serial M&C port, the
		ethernet port is always on and will not be affected).
Set Remote On	#	Just the ascii pound sign, (0x23)
		Will enable the unit's serial M&C port.
		The unit will reply with the '>' character if the command is
		sucessfully processed.
		(Note: this command only affects the serial M&C port, the
		ethernet port is always on and will not be affected).

2.0 Installation

2.1 Mechanical - The 2083-1617 consists of one RF/Controller PCB housed in a 1 RU (1 3/4 inch high) by 16 inch deep chassis. A switching, ± 12 , ± 24 , ± 5 VDC power supply provides power for the assemblies. The 2083-1617 can be secured to a rack using the 4 holes on the front panel. Figure 2.1 shows how the 2083-1617 is assembled.

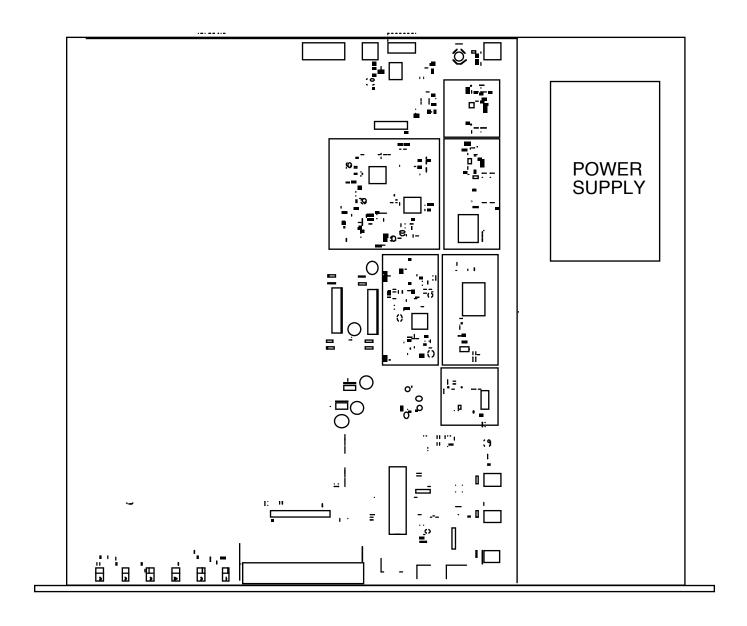
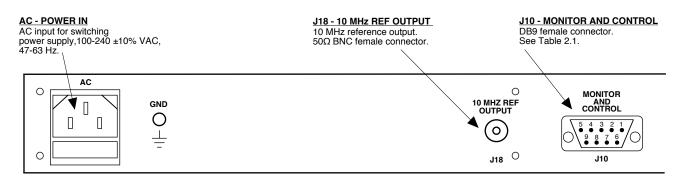


FIGURE 2.1 2083-1617 Mechanical Assembly

2.2 Rear Panel Input/Output Signals - Figure 2.2 shows the input and output connectors on the rear panel.



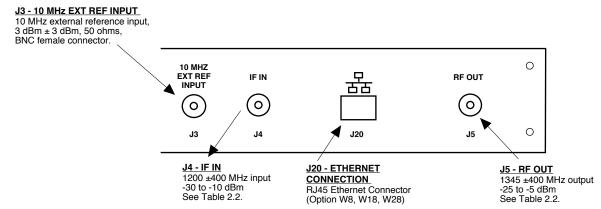


FIGURE 2.2 2083-1617 Rear Panel I/Os

TABLE 2.1 J10 Pinouts (RS-232C*)			
Pin	Function		
1	Not Used		
2	Rx+ (RS-232C)		
3	Tx+ (RS-232C)		
4	Not Used		
5	GND		
6	Alarm Relay: Common		
7	Alarm Relay: Normally Closed		
8	Not Used		
9	Alarm Relay: Normally Open		

*Remote Serial Interface

Interface: DB-9 Male

Protocol: RS-232C, 9600 baud rate, no parity, 8 data bits, 1 start bit, 1 stop bit

	TABLE 2.2 Connector/Impedance Options					
	Option	IF IN	RF Out			
L	STD	BNC, 50Ω	BNC, 50Ω			
L	-B	BNC, 75Ω	BNC, 75Ω			
	-NN	N for input	N for output			
	-SS	SMA, 50Ω	SMA, 50Ω			

2.3 Front Panel Controls and Indicators - The following are the front panel controls and indicators.

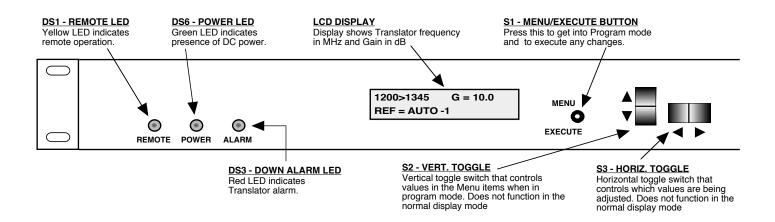


FIGURE 2.3 2083-1617 Front Panel Controls and Indicators

2.4 Operation

2.4.1 Installing and Operating the 2083-1617 Block Translator

- 1. Connect a -30 dBm to -10 dBm signal to IF IN, J4 (Figure 2.2)
- 2. Connect the RF OUT, J5, to the external equipment
- 3. Connect $100-240 \pm 10\%$ VAC, 47 63 Hz to AC on the back panel.
- 4. Set the gain for 0 to +20.0 dB (See Section 2.5 Menu Settings).
- 5. Be sure DS6 (green, DC Power) is on and DS (red, Alarm) is off (Figure 2.3).
- **6. AC Fuse** The fuse is a 5 mm X 20 mm, 2 amp slow blow (Type T) and is inserted in the far slot in the drawer below the AC input as shown in Figure 2.4. There is a spare fuse in the near slot. If a fuse continues to open, the power supply is most likely defective.

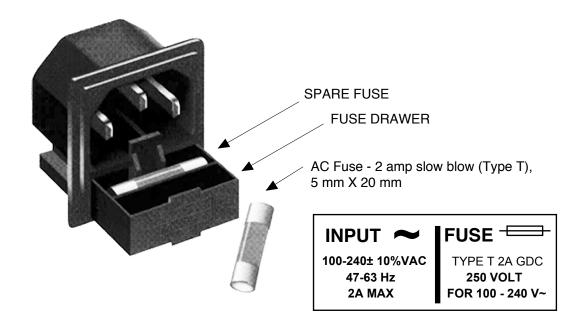


FIGURE 2.4 Fuse Location and Spare Fuse

2.5 Menu Settings

2.5.1 Functions - This section describes operation of the front panel controls. There are three operator switches, the LCD display and alarm indicator LEDs. All functions for the equipment are controlled by these components. The functions are (see Figure 2.5):

Power Up Normal Display

Menu 1 Gain (0 to +20.0, 0.5 dB Steps)
Menu 2 Set Unit to Remote Operation
Menu 3 Select External 10 MHz Ref
Menu 4 Set Remote mode (option -Q)
Menu 5 Set RS-485 address (option -Q)

Save Menu When go to "R" or at end

Alarm indications appear on the LEDs (See figure 2.3).

All program changes must start with the operation of the Menu/Execute switch and must also end with the operation of the Menu/Execute switch verified by the "Save Settings?" Menu. If this sequence is not followed, none of the changes will take effect. If programming is initiated and no operator action takes place for approximately 30 seconds (before the final press of the Menu/Execute switch) the display will revert to its previous status and you will need to start over.

2.5.2 Power On Settings

<u>NOTE</u>: THE LAST STATUS OF A UNIT IS RETAINED EVEN WHEN POWER IS REMOVED. WHEN POWER IS RESTORED, THE UNIT WILL RETURN TO IT'S PREVIOUS SETTINGS.

When power is first applied, the LCD display goes through three steps.

- 1. The LCD goes black to show all segments are functioning.
- 2. The software version will be displayed.

3. The present frequency and gain of the down converter is shown.

The unit is now operational and ready for any changes the operator may desire.

2.5.3 Control Switches

- 1. <u>Menu/Execute</u> Any change to the programming of the unit must be initiated by pressing the Menu/Execute switch and completed by pressing the Menu/Execute switch.
- 2. <u>Horizontal Switch</u> This switch is mounted so its movement is horizontal and moves the cursor left or right.
- 3. Vertical Switch This switch is mounted so its movement is vertical and has two functions:
 - a. During frequency, gain changes, the vertical movement will raise or lower the number in the direction of the arrows.
 - b. For other functions such Mute on/off, the vertical switch will alternately turn the function on or off regardless of the direction operated.

2.5.4 Gain Changes

When you get to this menu note that the gain changes will be made as you make them but if you do not wish to save the changes you have made, scroll to "R" and push the Menu/Execute switch and select "NO" in the "SAVE SETTINGS?" window or do not press the Menu/Execute switch; simply do nothing for approximately 12 seconds, and the system will return to the normal operating mode.

To change the TRANSLATOR GAIN:

Push the Menu/Execute switch to get to the gain setting (See Figure 2.5 for the sequence of menu options):

$$G = +20.0$$
 R

Pressing the Up/Down switch will change the gain in .5, 1 or 10 dB steps depending on the cursor location:

$$G = +15.0$$
 R

By using the horizontal rocker switch the cursor can be moved left or right. Pressing the Up/Down switch will toggle the display digit selected until you have the desired gain.

$$G = +15.0$$
 R

NOTE: THE GAIN WILL BE CHANGED AS YOU ADJUST THE NUMBERS. HOWEVER, THE VALUE WILL NOT BE STORED UNTIL YOU INDICATE YES IN THE SAVE SETTINGS WINDOW.

When the display indicates the value desired you can push the Menu/Execute switch to get to the next item OR you can scroll to "R" and push the Menu/Execute switch to get to:

Selecting \mathbf{Y} will save the new settings. Selecting \mathbf{N} will revert to the previous settings.

Pushing the Menu/Execute switch then takes you to this:

Figure 2.5 gives the menu items and how to make changes.

2.5.5 Alarm Indications

An alarm condition for will occur if any local oscillator phase lock loop (PLL) comes out of lock. The Remote LED will light when you select the Remote mode.

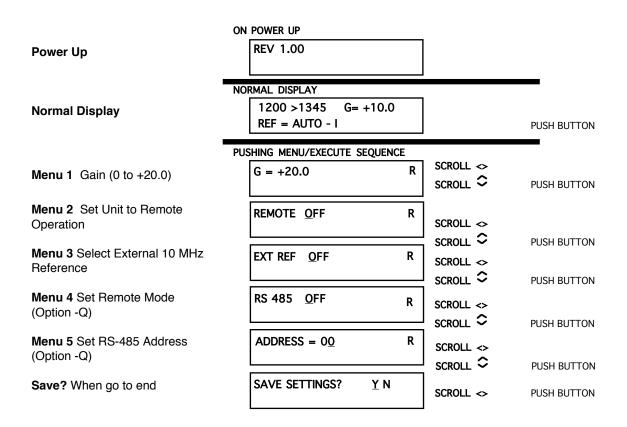


FIGURE 2.5 Menu Display and Sequence

3.0 Environmental Use Information

- **A.** Rack-Mounting To mount this equipment in a rack, please refer to the installation instructions located in the user manual furnished by the manufacturer of your equipment rack.
- **B.** Mechanical Loading Mounting of equipment in a rack should be such that a hazardous condition does not exist due to uneven weight distribution.
- C. Elevated Operating Ambient Temperature If installed in a closed or multi-unit rack assembly, the operating ambient temperature of the rack may be greater than room ambient temperature.

 Therefore, consideration should be given to Tmra (Maximum Recommended Ambient Temperature).
- **D.** Reduced Air Flow Installation of the equipment in a rack should be such that the amount of air flow required for safe operation of the equipment is not compromised. Additional space between units may be required.
- **E.** Circuit Overloading Consideration should be given to the connection of the equipment to the supply circuit and the effect that overloading of circuits could have on over current protection and supply wiring. Appropriate consideration of equipment name plate rating should be used when addressing this concern.
- **F. Reliable Earthing** Reliable earthing of rack-mounted equipment should be maintained. Particular attention should be given to supply connections other than direct connection to the Branch (use of power strips).
- **G. Top Cover** There are no serviceable parts inside the product so, the Top Cover should not be removed. If the Top Cover is removed the ground strap and associated screw MUST BE REINSTALLED prior to Top Cover screw replacement. FAILURE TO DO this may cause INGRESS and/or EGRESS emission problems.



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