## **Instruction Manual**

## Model 2083-1310 Block Translator

May 2018, Rev. 0

0				1500>1150 MAX IN=-30 REF = AUTO - I		MODEL 2083 TRANSLATOR	0
0	REMOTE	POWER	<b>O</b> ALARM		O V	<b>▲</b> ►	 0

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## **INSTRUCTION MANUAL**

## **MODEL 2083-1310 Block Translator**

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## MODEL 2083-1310 Block Translator

## 1.0 General

## **1.1 Equipment Description**

**2083-1310 Block Translator** - The 2083-1310 Block Translator converts a 1300-1700 MHz block to 950-1350 MHz block with no spectrum inversion, low group delay and flat frequency response. The 1300-1700 MHz input is mixed with synthesized local oscillator (LO) signals, first to 3800 MHz center frequency and finally to the 950-1350 MHz block output. The maximum input level (MAX IN) can be set for -20 to -40 dBm in  $1\pm1$  dB increments. Multifunction switches select the MAX IN and internal or External (Option E) 10 MHz reference which appear on the LCD display and can be adjusted remotely. Front panel LEDs provide indication of DC power (green), PLL alarm (red), and remote operation (yellow). Connectors are BNC female for RF input and output. The unit is powered by a 100-240  $\pm10\%$  VAC, 47-63 HZ input power supply and housed in a 1 3/4" X 19" X 16" rack mount chassis.

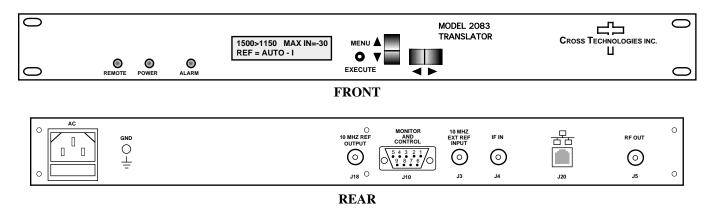
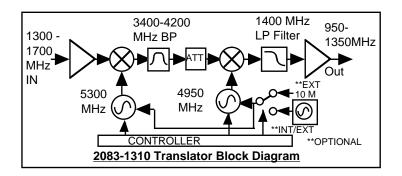


FIGURE 1.1 Model 2083-1310 Front and Rear Panels (Shown with optional Ethernet & Option E)



## FIGURE 1.2 Model 2083-1310 Translator Block Diagram

## **1.2 Technical Characteristics**

Input Impedance/RL	50Ω/12 dB				
Frequency	1300 - 1700 MHz				
Maximum Input Level Setting	-20 to -40 dBm, in 1±1dB steps				
Input Level Range	0 to -20 dB below MAX IN setting				
Noise Figure, Maximum	15 dB at -20 dBm	MAX IN setting			
Output Characteristics	1				
Impedance/RL	50Ω / 12 dB				
Frequency	950 - 1350 MHz				
Output Composite Level	-20 to - 60 dBm (	Maximum IN -20	to -40)		
Output 1 dB Compression	-10 dBm, at maxi	mum gain			
Channel Characteristics	1				
Gain, fixed	0 ± 1 dB at Fc an	d MAX IN set to -	20 dBm		
Frequency Response	± 1.5 dB, 400 MH	z bandwidth; ± 0	.5 dB, any 40 MH	z increment	
Spurious-Inband (Note 2)	< -50 dBC in ban	d, signal depende	ent & signal indep	endent; -20dBm o	ut; See NOTE
Spurious-Out of Band (Note 2)	< -30 dBC, 0.5- 0 -5 dBm out; See		6-2.1 GHz and 1.	30-1.70 GHz feed	through;
Frequency Sense	Non-inverting				
Group Delay	< 2ns, band; < 1	ns, any 65MHz			
	*NOTE 1: dBc is	relative to the CC	MPOSITE Outpu	t Level	
	*NOTE 2: Spurs	over MAX IN to M	IAX IN -20dB Rar	ige	
Synthesizer Characteristics	1				
Translation; Accuracy	1ppm; Option -H, ±0.01 ppm				
Reference	10 MHz Internal; Option -E, Internal/ External selection; external level 3±3 dBm				
Frequency Step	None, fixed frequ	iency			
Phase Noise @ Frequency	100 MHz	1kHz	10kHz	100kHz	1MHz
dBC/Hz	-70	-70	-80	-90	-100
Controls, Indicators					
Fc Translation	Direct readout L0	CD: manual or rer	note selection		
MAXIMUM IN Level	Direct readout L0				
External Ref. (Option -E)	Direct readout LC				
Power, Alarm; Remote Remote	Green LED; Red LED; Yellow LED RS232C, 9600 Baud; RS485, Ethernet Options				
Other	K3232C, 9000 B	auu, K3465, Elli			
RF In/RF Out Connector	PNIC (fomolo)				
	BNC (female)				
10 MHz Connector	BNC (female); 75				
Alarm/Remote Connector	DB9 (female); NC				
Size	19 inch Standard Chassis 1.75" high x 16.0" deep				
Size	100-240 (±10%)				

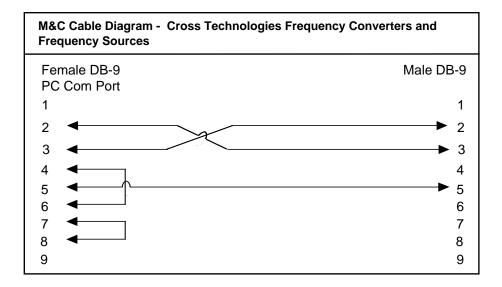
## 1.2 Technical Characteristics, continued...

Available Options (2083-1310 Block Translator)				
E -	External 10 MHz Input and Output			
Η-	High Stability (±0.01) Internal Reference			
Communication Interface / Sta	indard RS232			
Q -	RS485 Remote Interface			
W8 -	Ethernet; with Web Browser			
W18 -	Ethernet; with Web Browser & SNMP			
W28 -	Ethernet; with TCP/IP, Telnet®			
W828 -	Ethernet; W18 + W28			
Connectors /Impedance				
Std	50Ω BNC (RF In), 50Ω BNC (RF Out)			
NN -	50Ω N (RF In), 50Ω N (RF Out)			
SS -	50Ω SMA (RF In), 50Ω SMA (RF Out)			
Contact Cross Technologies for other options.				

#### **1.3 Monitor and Control Interface**

## A) Remote Serial Interface

**Protocol**: RS-232C, 9600 baud rate, no parity, 8 data bits, 1 start bit, and 1 stop bit. (RS-232C, RS-422, or **RS-485 - option -Q**)



Connector: Rear panel, DB-9 male

J10 Pinouts (RS-232C/422/485)				
Pin	Function			
1	Rx-			
2	Rx+ (RS-232C)			
3	Tx+ (RS-232C)			
4	Tx-			
5	GND			
6	Alarm Relay: Common			
7	Alarm Relay: Normally Open			
8	Not Used			
9	Alarm Relay: Normally Closed			

## B) Status Request/Inquiries -

Table 1.0 lists the Status Request/Inquiries for the **2083-0915**, **2083-1310**, **2083-1610** and briefly describes them.

General Command Format - The general command format is {aaCND...}, where:

- { = start byte
- aa = address (RS-485 only option Q)
- C = 1 character, either C (command) or S (status)
- N = 1 character command or status request
- D = 1 character or more of data (depends on command)
- } = stop byte

\* PLEASE NOTE: The two character {aa}(00-31) prefix, in the table below, should be used ONLY when RS-485, (OPTION-Q), is selected.

Command	Syntax*	Description
Max Input Level Inquiry	{aaSI}	returns: {aaSlxxx}
		where:
		aa = unit address, range = 00 to 31, only used if interface is
		RS485, otherwise omit
		I = command code
		xxx = maximum input level, range for each model as follows:
		The unit will reply with the '>' character if the command is
		sucessfully processed.
Reference Mode Inquiry	{aaSE}	returns: {aaSEx}
		where:
		aa = unit address, range = 00 to 31, only used if interface is
		RS485, otherwise omit
		E = command code
		x = 0 if reference mode is internal, $x = 1$ if external,
		x = 2 if auto
		The unit will append the '>' character if the command is
		sucessfully processed.
Reference Status Inquiry	{aaSB}	returns: {aaSBx}
		where:
		aa = unit address, range = 00 to 31, only used if interface
		is RS485, otherwise omit
		B = command code
		x = 1 if the unit is using the external reference, $x = 0$
		if the unit is using the internal reference
		note: this inquiry is useful if the reference mode is auto and
		the user wants to know if the unit has switched to the
		internal reference.
		The unit will append the '>' character if the command is
		sucessfully processed.

## Table 1.2, Status Request/Inquiries continued from page 7...

Command	Syntax*	Description
Alarm Inquiry	{aaSA}	returns: {aaSAx}
		where:
		aa = unit address, range = 00 to 31, only used if interface is
		RS485, otherwise omit
		A = command code
		x = 0 if alarm is off, $x = 1$ if alarm is on.
		The unit will append the '>' character if the command is
		sucessfully processed.
Product/Model Info Inquiry	{aaSV}	returns {aaSV2083-xxxx yyyy ver5.xx}
···		where 2083-xxxx = product model
		yyyy = list of options, if any
		"ver" = separates model & options from firmware version
		5.xx = firmware version

C) Commands - Table 1.0 lists the M&C Commands for the **2083-0915**, **2083-1310**, **2083-1610** and briefly describes them. After a command is sent the 2083-1310 sends a return ">" indicating the command has been received and executed.

**General Command Format** - The general command format is {aaCND...}, where:

- { = start byte
- aa = address (**RS-485 only option -Q**)
- C = 1 character, either C (command) or S (status)
- N = 1 character command or status request
- D = 1 character or more of data (depends on command)
- } = stop byte
- \* PLEASE NOTE: The two character {aa}(00-31) prefix, in the table below, should be used ONLY when RS-485, (OPTION-Q), is selected.

Command Function	Syntax*	Command Description		
Set Max Input Level	{aaClxxx}	where:		
		aa = unit address, range = 00 to 31,		
		only used if interface is RS485, otherwise omit		
		I = command code		
		xxx=maximum input level, range for each model as follows:		
		Model 2083-0915: minimum = -25 to -5 in 1 dBm steps		
		Model 2083-1310: minimum = -40 to -20 in 1 dBm steps		
		Model 2083-1610: minimum = -40 to -20 in 1 dBm steps		
		example: {CI-25}		
		Will set the unit's maximum input level to -25 dB.		
		Note: The negative sign is assumed if not included, i.e		
		{Cl25} is parsed the same as {Cl-25}.		
		The unit will reply with the '>' character if the command		
		is sucessfully processed.		
Set Reference Mode	{aaCEx}	where:		
		aa = unit address, range = 00 to 31, only used if interface		
		is RS485, otherwise omit.		
		E = command code		
		x = 0 to set to internal reference, $x = 1$ to set to		
		externa lreference, $x = 2$ to set to auto reference.		
		example: {CE2}		
		Will set the reference mode to Auto.		
		The unit will reply with the '>' character if the		
		command is sucessfully processed.		

## Table 1.3, M&C Commands, continued from page 9...

Command	Syntax*	Description
Set Remote Off	{aaCRO}	where:
		aa = unit address, range = 00 to 31, only used if interface is
		RS485, otherwise omit
		R = command code
		0, ascii number zero.
		example: {CRO}
		Will disable the unit's serial M&C port.
		The unit will reply with the '>' character if the command
		is sucessfully processed.
		(Note: this command only affects the serial M&C port, the
		ethernet port is always on and will not be affected).
Set Remote On	#	Just the ascii pound sign, (0x23)
		Will enable the unit's serial M&C port.
		The unit will reply with the '>' character if the command is
		sucessfully processed.
		(Note: this command only affects the serial M&C port, the
		ethernet port is always on and will not be affected).

## 2.0 Installation

**2.1 Mechanical** - The 2083-1310 consists of one RF/Controller PCB housed in a 1 RU (1 3/4 inch high) by 16 inch deep chassis. A switching,  $\pm 12$ ,  $\pm 24$ ,  $\pm 5$  VDC power supply provides power for the assemblies. The 2083-1310 can be secured to a rack using the 4 holes on the front panel. Figure 2.1 shows how the 2083-1310 is assembled.

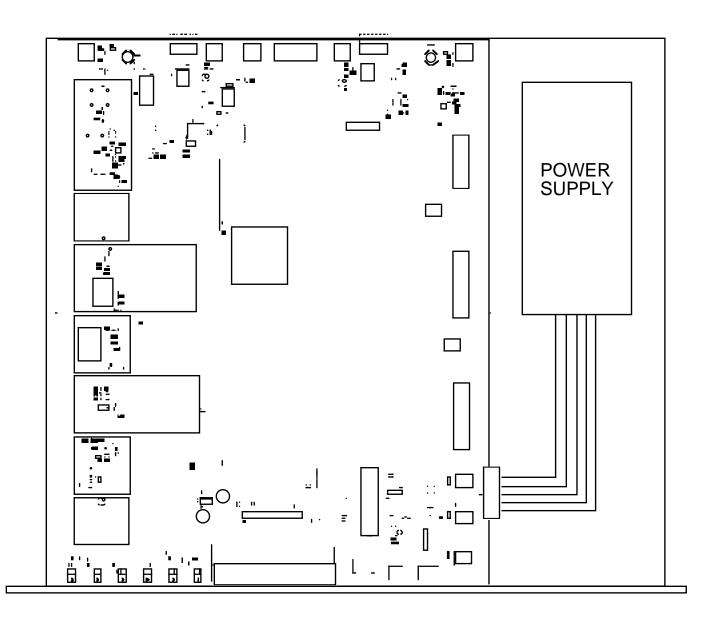
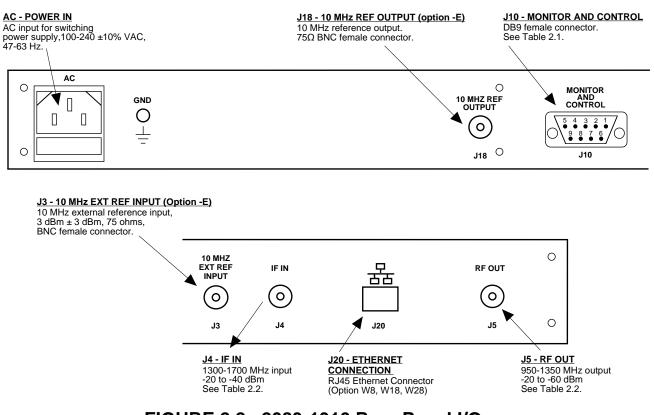


FIGURE 2.1 2083-1310 Mechanical Assembly

#### 2.2 Rear Panel Input/Output Signals - Figure 2.2 shows the input and output connectors on the rear panel.



## FIGURE 2.2 2083-1310 Rear Panel I/Os

TABLE 2.1 J10 Pinouts (RS-232C*)				
Pin	Function			
1	Not Used			
2	Rx+ (RS-232C)			
3	Tx+ (RS-232C)			
4	Not Used			
5	GND			
6	Alarm Relay: Common			
7	Alarm Relay: Normally Closed			
8	Not Used			
9	Alarm Relay: Normally Open			

#### **\*Remote Serial Interface**

Interface: DB-9 Male

Protocol: RS-232C, 9600 baud rate, no parity, 8 data bits, 1 start bit, 1 stop bit

TABLE 2.2 Connector/Impedance Options					
Option	IF Out	RF In			
STD	50 $Ω$ BNC	$50\Omega$ BNC			
-NN	50Ω N	50Ω N			
-SS	50Ω SMA	50 <b>Ω</b> SMA			

2.3 Front Panel Controls and Indicators - The following are the front panel controls and indicators.

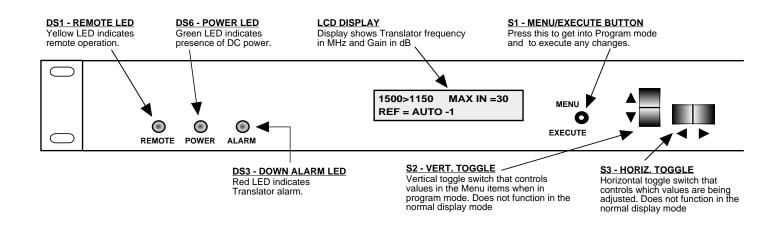


FIGURE 2.3 2083-1310 Front Panel Controls and Indicators

## 2.4 Operation

## 2.4.1 Installing and Operating the 2083-1310 Block Translator

- 1. Connect a -5 dBm to -25 dBm signal to IF IN, J4 (Figure 2.2)
- 2. Connect the RF OUT, J5, to the external equipment
- 3. Connect 100-240  $\pm$ 10% VAC, 47 63 Hz to AC on the back panel.
- 4. Set the Max. Input Level for -20 to -40 dBm (See Section 2.5 Menu Settings).
- 5. Be sure DS6 (green, DC Power) is on and DS (red, Alarm) is off (Figure 2.3).
- **6. AC Fuse -** The fuse is a 5 mm X 20 mm, 2 amp slow blow (Type T) and is inserted in the far slot in the drawer below the AC input as shown in Figure 2.4. There is a spare fuse in the near slot. If a fuse continues to open, the power supply is most likely defective.

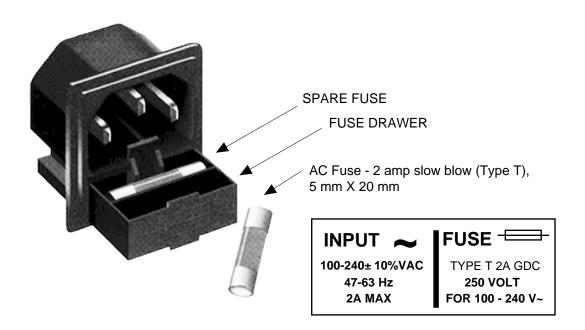


FIGURE 2.4 Fuse Location and Spare Fuse

## 2.5 Menu Settings

**2.5.1 Functions** - This section describes operation of the front panel controls. There are three operator switches, the LCD display and alarm indicator LEDs. All functions for the equipment are controlled by these components. The functions are (see Figure 2.5):

Power Up Normal Display		
Menu 1	Maximum Input Level	
Menu 2	Set Remote	
Menu 3	Select Referene Mode	
Menu 4	Reset Ethernet Settings	
Menu 5	Set Remote mode (option -Q)	
Menu 6	Set RS-485 address (option -Q)	

Save Menu When go to "R" or at end

Alarm indications appear on the LEDs (See figure 2.3).

All program changes must start with the operation of the Menu/Execute switch and must also end with the operation of the Menu/Execute switch verified by the "Save Settings?" Menu. If this sequence is not followed, none of the changes will take effect. If programming is initiated and no operator action takes place for approximately 30 seconds (before the final press of the Menu/Execute switch) the display will revert to its previous status and you will need to start over.

## 2.5.2 Power On Settings

## <u>NOTE</u>: THE LAST STATUS OF A UNIT IS RETAINED EVEN WHEN POWER IS REMOVED. WHEN POWER IS RESTORED, THE UNIT WILL RETURN TO IT'S PREVIOUS SETTINGS.

When power is first applied, the LCD display goes through three steps.

1. The LCD goes black to show all segments are functioning.

2. Reading IP Address

2. The software version will be displayed.

#### **READING IP ADDRESS**

3. The present frequency and gain of the down converter is shown.

```
1500>1150 MAX IN = -30
REF=AUTO - 1
```

The unit is now operational and ready for any changes the operator may desire.

#### 2.5.3 Control Switches

- 1. <u>Menu/Execute</u> Any change to the programming of the unit must be initiated by pressing the Menu/Execute switch and completed by pressing the Menu/Execute switch.
- 2. <u>Horizontal Switch</u> This switch is mounted so its movement is horizontal and moves the cursor left or right.
- 3. <u>Vertical Switch</u> This switch is mounted so its movement is vertical and has two functions:
  - a. During frequency, gain changes, the vertical movement will raise or lower the number in the direction of the arrows.
  - b. For other functions such Mute on/off, the vertical switch will alternately turn the function on or off regardless of the direction operated.

## 2.5.3 Maximum Input Level

To change the MAXIMUM INPUT LEVEL:

Push the Menu/Execute switch to get to the Maximum Input Level (See Figure 2.5 for the sequence of menu options):



Pressing the Up/Down switch will change the Maximum Input Level in 1 or 10 dB steps depending on the cursor location:

```
MAX INPUT LEVEL = R
-<u>2</u>0
```

By using the horizontal rocker switch the cursor can be moved left or right. Pressing the Up/Down switch will toggle the display digit selected until you have the desired gain.

```
MAX INPUT LEVEL = R
-40
```

## NOTE: THE MAXIMUM INPUT LEVEL WILL BE CHANGED AS YOU ADJUST THE NUMBERS. HOWEVER, THE VALUE WILL NOT BE STORED UNTIL YOU INDICATE YES IN THE SAVE SETTINGS WINDOW.

When the display indicates the value desired you can push the Menu/Execute switch to get to the next item OR you can scroll to "R" and push the Menu/Execute switch to get to:

```
SAVE SETTINGS? \underline{Y} N
```

Selecting **Y** will save the new settings. Selecting **N** will revert to the previous settings. Pushing the Menu/Execute switch then takes you to this:

```
1500>1150 MAX IN = -30
REF=AUTO - 1
```

Figure 2.5 gives the menu items and how to make changes.

## **2.5.4 Alarm Indications**

An alarm condition for will occur if any local oscillator phase lock loop (PLL) comes out of lock. The Mute LED will light if you select Mute and the Remote LED will light when you select the Remote mode.

	ON POWER UP	
Power Up	REV 1.00	
Normal Display	NORMAL DISPLAY	1
Normal Display	1500>1150 MAX IN=30 REF = AUTO-1	
		PUSH BUTTON
	PUSHING MENU/EXECUTE SEQUENCE	
Menu 1 Max Input Level	MAX INPUT LEVEL = R	SCROLL <>
	-25	SCROLL C PUSH BUTTON
Menu 2 Set Remote	REMOTE ON R	SCROLL <>
		SCROLL C PUSH BUTTON
	REF MODE = AUTO R	SCROLL <>
Menu 3 Set Reference Mode	REF MODE = AUTO R	SCROLL C PUSH BUTTON
Manu A Pagat Ethernat Sattinga		
Menu 4 Reset Ethernet Settings	RESET ETHERNET R	SCROLL <>
Menu 5 Set Remote Mode	SETTINGS <u>O</u> N	SCROLL C PUSH BUTTON
(Option -Q)	RS 485 OFF D	
	RS 485 <u>O</u> FF R	SCROLL <>
Menu 6 Set RS-485 Address		SCROLL C PUSH BUTTON
(Option -Q)	ADDRESS = $O\underline{O}$ R	SCROLL <>
		SCROLL <b>C</b> PUSH BUTTON
Save? When go to end	SAVE SETTINGS? Y N	SCROLL <> PUSH BUTTON

FIGURE 2.5 Menu Display and Sequence

## 3.0 Environmental Use Information

- **A. Rack-Mounting** To mount this equipment in a rack, please refer to the installation instructions located in the user manual furnished by the manufacturer of your equipment rack.
- **B.** Mechanical Loading Mounting of equipment in a rack should be such that a hazardous condition does not exist due to uneven weight distribution.
- C. Elevated Operating Ambient Temperature If installed in a closed or multi-unit rack assembly, the operating ambient temperature of the rack may be greater than room ambient temperature. Therefore, consideration should be given to Tmra (Maximum Recommended Ambient Temperature).
- **D. Reduced Air Flow** Installation of the equipment in a rack should be such that the amount of air flow required for safe operation of the equipment is not compromised. Additional space between units may be required.
- **E.** Circuit Overloading Consideration should be given to the connection of the equipment to the supply circuit and the effect that overloading of circuits could have on over current protection and supply wiring. Appropriate consideration of equipment name plate rating should be used when addressing this concern.
- **F. Reliable Earthing** Reliable earthing of rack-mounted equipment should be maintained. Particular attention should be given to supply connections other than direct connection to the Branch (use of power strips).
- **G.** Top Cover There are no serviceable parts inside the product so, the Top Cover should not be removed. If the Top Cover is removed the ground strap and associated screw MUST BE REINSTALLED prior to Top Cover screw replacement. FAILURE TO DO this may cause INGRESS and/or EGRESS emission problems.

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